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Solution: The key is to draw the Free

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Body Diagram (FBD) in order to keep the signs right. To identify the direction of the spring forces on the left side object, let $x_2 = 0$ and increase x_1 from 0. Then the k_1 spring on the left will be stretched producing its spring force to the left and the k_2 spring

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a) Design a state feedback controller for
the following system so that the closed-

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loop step response has an overshoot of less than 5% and a 1% settling time under 4.6 sec. b) Use the step command in MATLAB to verify that your design meets the specifications. If it does not, modify your feedback gains accordingly.

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Chapter 3 Dynamic Response
Problems and Solutions for Section 3.1
1. Show that,

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location of the elements listed below and give the units associated with each signal.

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point of the left pendulum from the free body diagram, $M = ml^2$ •

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